# Self-equivalences of dihedral spheres 

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#### Abstract

Let $G$ be a finite group. The group of homotopy self-equivalences $\mathcal{E}_{G}(X)$ of an orthogonal $G$-sphere $X$ is related to the Burnside ring $A(G)$ of $G$ via the stabilization map $I: \mathcal{E}_{G}(X) \subset[X, X]_{G} \rightarrow\{X, X\}_{G}=A(G)$ from the set of $G$-homotopy classes of self-equivalences of $X$ to the ring of stable $G$-homotopy classes of self-maps of $X$ (that is, the 0 -th dimensional $G$-homotopy group of $S^{0}$, which is isomorphic to the Burnside ring). As a consequence of the properties of $I$, $\mathcal{E}_{G}(X)$ is equal to an extension of a subgroup of the group of units in $A(G)$ with the kernel of $I$. The aim of the paper is to give examples of a family of equivariant (dihedral) spheres with the property that the kernel of $I$ is a non-abelian torsionfree group with many generators, and to give estimates on the structure of $\mathcal{E}_{G}(X)$ itself.


## 1. Introduction

Let $S^{n}$, with $n>0$, denote the sphere of dimension $n$. The canonical stabilization map $I$ sending homotopy classes of self-maps to stable homotopy classes is a bijection from [ $S^{n}, S^{n}$ ] to $\left\{S^{n}, S^{n}\right\}$. Moreover, the group of self homotopy equivalences $\mathcal{E}\left(S^{n}\right)$ of $S^{n}$ is the finite cyclic group of order 2 . On the other hand, if we consider equivariant spheres in the category of $G$-spaces and $G$-maps (with $G$ finite group) these properties do not hold. If $S$ is a $G$-sphere, it can be that the canonical stabilization map $I:[S, S]_{G} \rightarrow$

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$\{S, S\}_{G}=A(G)$ from the monoid of equivariant homotopy classes of self-maps of $S$ to the ring of stable homotopy classes of self-maps (which is isomorphic to the 0-th dimensional equivariant homotopy group of $S^{0}$ and to the Burnside ring of the group $G)$ is not a bijection. It is trivial to see that it can be not onto, and it was first found by Rubinsztein [5] that it can be not mono.

This idea can be applied to the problem of homotopy self-equivalences of equivariant spheres, in the framework of the classical results relating equivariant stable homotopy theory to ordinary stable homotopy theory (dating back to the works of G. Segal, A. Kosinski, T. tom Dieck and H. Hauschild): it is easy to see that $I$ sends the group of equivariant homotopy self-equivalences $\mathcal{E}_{G}(S) \subset[S, S]_{G}$ to the group of units $A(G)^{*}$ of the Burnside ring (which is a finite abelian 2-group). As before, it is trivial to see that the image $I \mathcal{E}_{G}(S)$ can be properly contained in $A(G)^{*}$, and that $I$ can be non-injective even if restricted to $\mathcal{E}_{G}(S)$. The purpose of this paper is to provide some examples of equivariant spheres with the property that the kernel of $I: \mathcal{E}_{G}(S) \rightarrow A(G)^{*}$ is an infinite non-abelian group. Actually, we produce a family of spheres $X_{k}$, with $k=2 \ldots \infty$, equivariant with respect to a suitable group $G_{k}$ depending upon $k$, such that the following theorem holds:

## Theorem 1

The group of homotopy self-equivalences $\mathcal{E}_{G_{k}}\left(X_{k}\right)$ is an extension of the kernel of the stabilization map I by a subgroup of order $2^{2^{k}-1}$ and index 4 in the group of units of the Burnside ring $A(G)^{*}$ :

$$
\begin{equation*}
I: \operatorname{ker} I>\mathcal{E}_{G_{k}}\left(X_{k}\right) \rightarrow \mathbb{Z}_{2}^{2^{k}-1} \subset A\left(G_{k}\right)^{*}=\mathbb{Z}_{2}^{2^{k}+1} . \tag{1}
\end{equation*}
$$

The kernel ker $I$ is a non-abelian torsion-free solvable group of Hirsch length $h(\operatorname{ker} I)=$ $3^{k}-2^{k}-k$ and derived length $l(\operatorname{ker} I)$ bounded by

$$
\begin{equation*}
\frac{k}{2} \leq l\left(G_{k}\right) \leq k-1 \tag{2}
\end{equation*}
$$

The interesting fact is that therefore $\operatorname{ker} I$ is never trivial, for $k \geq 2$, and it is always non-abelian, for $k \geq 3$.

In the last decades many results have been proved about homotopy self-equivalences: for general surveys and the state-of-the-art we refer to the well-known references $[6,4,3]$. In $[3]$ one can find a complete and up-to-date bibliography.

I sincerely wish to express my thanks to the referee, who improved significantly the results of the paper with some generous comments.

## 2. Preliminaries

If $G$ is a group acting on a space $X$, then let $G_{x}$ be the isotropy group of $x$ (that is, the stabilizer of $x$, or the fixer of $x$ ), $G_{x}=\{g \in G \mid g x=x\}$. Then the space of the points fixed by a subgroup $K \subset G$ is denoted by $X^{K}=\{x \in X \mid K x=x\}$; the singular set
of $X^{K}$ is $X_{s}^{K}=\left\{x \in X^{K} \mid G_{x} \neq K\right\}$. If $f: X \rightarrow X$ is a $G$-equivariant map and $K$ a subgroup of $G$, the restriction of $f$ to $X^{K}$ is denoted by $f^{K}: X^{K} \rightarrow X^{K}$. The isotropy type of an isotropy group $K \subset G$ is the conjugacy class of $K$ and is denoted with ( $K$ ). The normalizer of the subgroup $K$ of $G$ in $G$ is denoted by $N_{G} K$ and is equal to $\left\{g \in G \mid g K g^{-1}=K\right\}$. The Weyl group $W_{G} K$ is equal to the quotient $N_{G} K / K$. The monoid (with respect to composition of maps) of free $G$-homotopy classes of self-maps of $X$ is denoted by $[X, X]_{G}$; the ring of stable $G$-homotopy classes of selfmaps of $X$ is denoted by $\{X, X\}_{G}$. If $X$ is a sphere, then $\{X, X\}_{G}$ is isomorphic to the Burnside ring $A(G)$ (e.g. via the equivariant degree homomorphism). The equivariant degree homomorphism is defined as follows: for every $f: X \rightarrow X$ and for every conjugacy class $(K)$, let $d_{G}(f)(K)=\operatorname{deg}\left(f^{K}\right)$. If all the subgroups of $G$ are of isotropy, then this defines a homomorphism $\operatorname{deg}_{G}:[X, X]_{G} \rightarrow \prod_{(K)} \mathbb{Z}$ inducing a homomorphism $\operatorname{deg}_{G}:\{X, X\}_{G} \rightarrow \prod_{(K)} \mathbb{Z}$. Now, if $\operatorname{dim} X^{G} \geq 1$ then the image $\operatorname{deg}_{G}\{X, X\}_{G} \subset \prod_{(K)} \mathbb{Z}$ coincides with the image of the Burnside ring $A(G)$ in its ghost ring $\prod_{(K)} \mathbb{Z}$ (see e.g. the last chapter of [7] for more details), and therefore $A(G)$ is isomorphic to $\{X, X\}_{G}$ in a canonical way. This isomorphism actually can be seen as the definition itself of $A(G)$ in case $G$ is a compact Lie group.

We recall that the derived length $l(G)$ of a (solvable) group $G$ is the length of the shortest abelian series in $G$ (i.e. the number of its non-trivial factors). A group has derived length 0 if it is trivial, 1 if it is abelian. If the length is at least 2 , the group is non-abelian. The Hirsch length $h(G)$, also known as torsion-free rank, of a group $G$ is the number of infinite cyclic factors in a polycyclic decomposition of $G$, that is the number of infinite factors in a series of finite length with factors which are either torsion or infinite cyclic groups.

## 3. Dihedral spheres

Let $n \geq 2$ be an integer; let $\zeta_{n}$ and $h$ be the transformations of the complex plane $\mathbb{C}$ defined by $\zeta_{n}(z)=e^{(2 \pi i) / n} z$ and $h(z)=\bar{z}$, for every $z \in \mathbb{C}$. With an abuse of notation it is possible to write $\zeta_{n}=e^{(2 \pi i) / n}$. With the symbol $D_{2 n}$ we denote the dihedral group of order $2 n$, generated by $\zeta_{n}$ and $h$. Let $G$ be equal to $D_{2 n}, N \subset G$ the normal subgroup of $G$ generated by $\zeta_{n}$ and $H$ the subgroup generated by $h$.

For any integer $j$ let $V(j)$ be the (2-dimensional real) linear representation of $D_{2 n}$ given by the action $\zeta_{n} \cdot z=\zeta_{n}^{j} z$ and $h \cdot z=\bar{z}$. Therefore the space fixed by the element $\zeta_{n}^{\alpha} \in G$, with $\alpha=0 \ldots n-1$, is

$$
(V(j))^{\zeta_{n}^{\alpha}}=\left\{\begin{array}{ll}
V(j) & \text { if } \quad \alpha j \equiv 0 \bmod n \\
0 & \text { if } \quad \alpha j \not \equiv 0 \bmod n
\end{array},\right.
$$

while the space fixed by the element $\zeta_{n}^{\alpha} h \in G$, with $\alpha=0 \ldots n-1$ is $(V(j))^{\zeta_{n}^{\alpha} h}=$ $\left\langle e^{\alpha j \pi / n i}\right\rangle$, where $\langle z\rangle$ denotes the one-dimensional subspace of the vector space $V(j)$ over $\mathbb{R}$ generated by the element $z$.

If $j_{1}, j_{2}, \ldots, j_{k}$ are integers, with $k \geq 2$, then let $D\left(j_{1}, j_{2}, \ldots, j_{k}\right)$ denote the unit sphere in $V\left(j_{1}\right) \oplus V\left(j_{2}\right) \oplus \ldots \oplus V\left(j_{k}\right)$, endowed with the $D_{2 n}$-action. Assume that $n=p_{1} p_{2} \ldots p_{k}$ is the product of the $k$ first odd primes $p_{i}$. We denote the corresponding dihedral group with $G_{k}$. For every $i=1 \ldots k$, let $j_{i}=n / p_{i}$, and $X_{k}$ the unit sphere $D\left(j_{1}, j_{2}, \ldots, j_{k}\right)$ for such a choice of $j_{i}$.

Some properties of $X$ and $G$ are the following:
(i) Two subgroups of $G_{k}$ are conjugated if and only if they have the same order.
(ii) The minimal non-trivial subgroups of $G_{k}$ (up to conjugacy) are the cyclic normal groups of order $p_{i}$ generated by $\zeta_{n}^{j_{i}}$ and $H=\langle h\rangle$.
(iii) The normal proper subgroups of $G_{k}$ have odd order.
(iv) All the subgroups of $G_{k}$ are isotropy subgroups, except $G_{k}$ and the normal subgroup of index 2 .

The first three statements are simple. The fourth is a consequence of the following computations. The space fixed by $H$ is a $(k-1)$-dimensional sphere; it is the unit sphere in the vector space of the real parts of the $V\left(j_{i}\right)$, with $i=1 \ldots k$. The Weyl group $W_{G} H$ is trivial. The singular set $X_{s}^{H}$ in $X^{H}$ is given by the points in $X^{H}$ with coordinates $\left(z_{1}, z_{2}, \ldots, z_{k}\right)$ such that $\prod_{i=1}^{k} z_{i}=0$ (that is, such that at least one coordinate is zero; it is the union of the intersections of the hyperplanes $z_{i}=0$ with $\left.X^{H}\right)$. Actually, the isotropy group of a point $\left(z_{1}, z_{2}, \ldots, z_{k}\right)$ is the intersection of the isotropy groups of $z_{i} \in V\left(j_{i}\right)$, for $i=1 \ldots k$. The principal isotropy type in $X$ is trivial. Therefore the trivial subgroup of $G$ is isotropy. Moreover, the singular set $X_{s}$ is the union of the points fixed by the minimal cyclic subgroups of $G_{k}$. That is, the $n$ conjugated copies of $H$ fix $(k-1)$-spheres, while the normal cyclic groups $<\zeta_{n}^{j_{i}}>$ fix the $(2 k-3)$-sphere of equation $z_{i}=0$. The Weyl groups act on such spheres, and they are $G^{\prime}$-homeomorphic to equivariant $G^{\prime}$-spheres defined as $D\left(j_{1}^{\prime}, \ldots, j_{k-1}^{\prime}\right)$ for suitable $j_{i}^{\prime}$ and a suitable homomorphic image $G^{\prime}$ of $G$ (the Weyl groups themselves). More precisely, there are two kind of subgroups in $G$ : normal and non-normal (i.e. odd order or even order): the space fixed by a normal subgroup $N \triangleleft G$ is, regarded as a $G / N$-space, equivariantly homeomorphic to a $G / N$-sphere $D\left(j_{1}^{\prime}, \ldots, j_{k^{\prime}}^{\prime}\right)$ for suitable $j_{i}^{\prime}$ and $k^{\prime}<k ; k^{\prime}$ is equal to the number of minimal odd-order cyclic subgroups $G$ not contained in $N$. On the other hand, the space fixed by a non-normal subgroup $K$ (which has always trivial Weyl group) is equal to $D\left(j_{1}^{\prime}, \ldots, j_{k^{\prime}}^{\prime}\right)^{H^{\prime}}$ for suitable $j_{i}^{\prime}$ and $k^{\prime}<k$, where $H^{\prime}$ denotes the minimal subgroup of order 2 in $G / N_{0}$ and $N_{0}$ denotes the maximal subgroup of $K$ normal in $G$. That is, it is again equal to a sphere of dimension $k^{\prime}-1$ with as singular set the coordinates hyperplanes (if $k^{\prime}>0$ ). Like before, $k^{\prime}$ is equal to the number of minimal cyclic odd-order subgroups not in $N_{0}$. If $k^{\prime}=1$, then $X^{K}$ is a zero-dimensional sphere. If $k^{\prime}=0$, that is if $N_{0}$ has order $n$, then clearly $K=G$ and hence the fixed point set is empty.

## 4. Some results on equivariant spheres

Let $G$ be a finite group and $X$ be an orthogonal $G$-sphere. Consider the stabilization $\operatorname{map} I: \mathcal{E}_{G}(X) \rightarrow A(G)^{*}$. If $K$ is an isotropy group in $G$ for $X$, then let $\gamma_{K}$ denote the number of positive-dimensional components of the space $X_{(K)} / G$ (which is the subspace of the orbit space $X / G$ of the elements with isotropy type equal to $(K)$ ). It is not difficult to see that it is homeomorphic to $X_{K} / W_{G} K$. These numbers will play a key role in the computation of the kernel of $I$.

## Proposition 2

The kernel ker $I$ of $I: \mathcal{E}_{G}(X) \rightarrow A(G)^{*}$ is a torsion-free solvable group, with Hirsch length equal to

$$
h(G)=\sum_{(K)}\left(\gamma_{K}-1\right)
$$

where $\gamma_{K}$ as above is equal to $\left|\pi_{0}\left(X_{K} / W_{G} K\right)\right|$ and ( $K$ ) ranges over the set of isotropy classes such that $\operatorname{dim} X^{K} \geq 1$.

Proof. As a consequence of Theorem 1.1 of [2], there is an abelian series

$$
1=\operatorname{ker} I_{N} \subset \operatorname{ker} I_{N-1} \ldots \subset \operatorname{ker} I_{1} \subset \operatorname{ker} I_{0}=\operatorname{ker} I
$$

such that

$$
\frac{\operatorname{ker} I_{j-1}}{\operatorname{ker} I_{j}} \cong \begin{cases}\mathbb{Z}^{\left(\gamma_{K_{j}}-1\right)} & \text { if } \operatorname{dim} X^{K_{j}}>0 \\ 0 & \text { if } \operatorname{dim} X^{K_{j}}=0\end{cases}
$$

where $N$ is the number of isotropy types in $X$. This implies the proposition.

## Proposition 3

The kernel ker $I$ of $I: \mathcal{E}_{G}(X) \rightarrow A(G)^{*}$ has derived length $l(\operatorname{ker} I) \leq d$, where $d$ denotes the maximum dimension of spheres in $X$ fixed by subgroups $K$ such that $\gamma_{K} \geq 2$ and $\operatorname{dim} X^{K} \geq 1$.

Proof. Let $X^{d}$ denote the union in $X$ of all the spheres of dimension at most $d$ fixed by some non-trivial elements in $G$, with $0 \leq d$. It is a $G$-invariant subspace, and therefore there is a well-defined homomorphism (with respect to composition of maps) given by restriction $r_{i}: \operatorname{ker} I \rightarrow\left[X^{i}, X^{i}\right]^{\text {str }}$, where the latter symbol denotes the homotopy classes of maps preserving the stratification $X^{i} \supset X^{i-1} \supset \ldots X^{0}$. A homotopy class $f$ is in $\operatorname{ker} r_{i}$ if and only if it is $G$-homotopic to a map which is the identity on $X^{i}$. The kernels ker $r_{i}$ are a chain of subgroups of $\operatorname{ker} I$ such that

$$
1 \triangleleft \operatorname{ker} r_{d} \triangleleft \operatorname{ker} r_{d-1} \triangleleft \ldots \triangleleft \operatorname{ker} r_{0} \triangleleft \operatorname{ker} I
$$

and ker $r_{i} / \operatorname{ker} r_{i+1}$ can be embedded in the product $\prod_{K}\left[X^{K}, X^{K}\right]_{X_{s}^{K}}^{*}$ of groups of the self-equivalences of $X^{K}$ which are the identity on $X_{s}^{K}$, modulo relative homotopy and with $\operatorname{dim} X^{K}=i+1$. But this is a product of abelian groups, thus the series $\operatorname{ker} r_{i}$
has abelian factors. On the other hand it is not difficult to see that ker $r_{d}=1$ (this is a consequence of the fact that if $K$ is the principal isotropy type in $X$ then $\gamma_{K}=1$ ) and that $\operatorname{ker} I=\operatorname{ker} r_{0}$, because there are no self-equivalences in spheres of dimension 0 which are not detected by the degree. Thus the abelian series is actually of length d.
The following corollary is an immediate consequence of Proposition 3. Note that if the proof of Proposition 3 had been carried out directly on $\mathcal{E}_{G}(X)$, then the upper bound would have been $d+2$ instead of $d+1$.

## Corollary 4

The group of homotopy self-equivalences $\mathcal{E}_{G}(X)$ is a solvable group with derived length at most $d+1$ and at least $l(\operatorname{ker} I)$.

## 5. Homotopy self-equivalences of $X_{k}$

Now let $k \geq 2$ and go back to the equivariant sphere $X=X_{k}$ defined in Section 3 . All the proper subgroups (other than the normal subgroup of index 2) of $G_{k}$ are of isotropy, and there is just one conjugacy class for each order. Let $H$ be the isotropy subgroup generated by $h \in G_{k}$ as above. The complement of the singular part $X_{s}^{H}$ in $X^{H}$ has $2^{k}$ components. Because the Weyl group $W_{G} H$ is trivial, $\gamma_{H}=2^{k}$. On the other hand, since the minimal cyclic subgroups $N$ of odd order are normal, it is $\gamma_{N}=1$. Now, because of the recursive property sketched at the end of Section 2 , this is what happens in general to the subgroups: if $K$ is a normal subgroup of $G$ them $\gamma_{K}=1$; otherwise, $K$ is isomorphic to $N_{0} \rtimes \mathbb{Z}_{2}$ for a suitable subgroup $N_{0}$ normal in $G$, and $W_{G} K=1$. Moreover, in this case the space $X^{K}$ is equal to a sphere of dimension $k^{\prime}-1$, and the singular set $X_{s}^{K}$ to the intersection with the coordinates hyperplanes. Thus, again $\gamma_{K}=2^{k^{\prime}}$.

## Proposition 5

The kernel ker I of the stabilization map

$$
I: \mathcal{E}_{G}\left(X_{k}\right) \rightarrow A(G)^{*}
$$

is a torsion-free solvable group of Hirsch length

$$
h\left(G_{k}\right)=3^{k}-2^{k}-k
$$

Proof. Because of Proposition 2, ker $I$ is a torsion-free solvable group of Hirsch rank

$$
\sum_{(K)}\left(\gamma_{K}-1\right)
$$

The sum ranges over all the isotropy types of $G$ such that $\operatorname{dim} X^{K} \geq 1$; if $K$ is normal then $\gamma_{K}=1$, therefore the sum ranges over all the conjugacy classes of subgroups in $G$ that are non-normal, and such that $\operatorname{dim} X^{K} \geq 1$. These consist of all the evenorder proper subgroups of $G$. The number conjugacy classes of such subgroups fixing a sphere of dimension $d-1$ is equal, up to conjugacy, to $\binom{k}{d}$. Thus the rank of ker $I$ is equal to

$$
\mathrm{rk}=\sum_{\mathrm{d}=2}^{\mathrm{k}}\binom{\mathrm{k}}{\mathrm{~d}}\left(2^{\mathrm{d}}-1\right)=3^{\mathrm{k}}-2^{\mathrm{k}}-\mathrm{k}
$$

This completes the proof.

## Proposition 6

The image of $\mathcal{E}_{G_{k}}\left(X_{k}\right)$ in $A(G)^{*}$ under the stabilization map $I$ is a subgroup of index 4 in $A(G)^{*}$.

Proof. The double suspension of the self-join $\Sigma^{2} X_{k} * X_{k}$, with diagonal action on $X_{k}$ has the property that all the subgroups of $G_{k}$ are isotropy ( $G_{k}$ and the maximal normal subgroup $N$ are the only subgroups of $G$ that are isotropy for $\Sigma^{2} X_{k} * X_{k}$ but not for $X_{k}$ ) and that

$$
\left[\Sigma^{2} X_{k} * X_{k}, \Sigma^{2} X_{k} * X_{k}\right]_{G_{k}}=\left\{X_{k}, X_{k}\right\}_{G_{k}}=A\left(G_{k}\right)
$$

(see [5]); hence the index of the image of the stabilization map in $A\left(G_{k}\right)^{*}$

$$
I: \mathcal{E}_{G_{k}}\left(X_{k}\right) \rightarrow A\left(G_{k}\right)^{*}=\mathcal{E}_{G_{k}}\left(\Sigma^{2} X_{k} * X_{k}\right)
$$

is equal to the index of the image of $\mathcal{E}_{G_{k}}\left(X_{k}\right)$ in $\mathcal{E}_{G_{k}}\left(\Sigma^{2} X_{k} * X_{k}\right)$, under the inclusion given by $f \mapsto \Sigma^{2} f * 1$. It is not difficult to show that this has index 4 , by the method given in [2], so the proof follows. Compare with the proof of the following proposition, where the method is applied directly.

## Proposition 7

The group of units in the Burnside ring $A\left(G_{k}\right)^{*}$ is an elementary abelian 2-group of order $2^{2^{k}+1}$.

Proof. Consider again $\mathcal{E}_{G_{k}}\left(\Sigma^{2} X_{k} * X_{k}\right)$ : the degree homomorphism

$$
d_{G}: \mathcal{E}_{G_{k}}\left(\Sigma^{2} X_{k} * X_{k}\right) \rightarrow \prod_{(K)} \mathbb{Z}^{*} \subset \prod_{(K)} \mathbb{Z}
$$

is mono, and hence, by applying again Theorem 1.1 of [2], it is obtained that $A(G)^{*}$ is an elementary abelian 2-group with at most $\kappa\left(\Sigma^{2} X_{k} * X_{k}\right)$ generators, where $\kappa$ denotes the number of isotropy groups with Weyl group of order at most 2. In our case, there are exactly $2^{k}$ conjugacy classes of subgroups with trivial isotropy, and one conjugacy class with index 2 in $G_{k}$ (the maximal normal subgroup of $G_{k}$ ). Therefore, $\kappa=2^{k}+1$, and therefore the order of $A\left(G_{k}\right)^{*}$ is at most $2^{2^{k}+1}$. To show that this is actually
an equality, we proceed by using the fact that the order of $A(G)^{*}$ is the number of solutions of the equation $y \cdot T \in\{0,2\}^{2^{k+1}}$, where $2^{k+1}$ is the number of conjugacy classes of subgroups of $G_{k}, T$ is the table of marks matrix of $G_{k}$, that is the $2^{k+1} \times 2^{k+1}$ lower triangular matrix with entries equal to $\left|\left(\frac{G}{K}\right)^{H}\right|$ (the cardinality of the fixed point set of the action of $H$ on the set of left $K$-cosets in $G$; see [2] for further details); and $y$ is a $2^{k+1}$-dimensional row vector of integers. Let $y_{K}$ denote the entry corresponding to the conjugacy class of subgroups $(K)$. We can rewrite the same system of equations as

$$
\begin{equation*}
\forall(H) \leq(G): \quad \sum_{(K) \geq(H)} y_{K}\left|\left(\frac{G}{K}\right)^{H}\right| \in\{0,2\} \tag{3}
\end{equation*}
$$

Consider now first the subgroups $K \subset G$ belonging to the following class $\mathcal{I}$ : either they are self-normalizing, or of index 2 in $G$. These subgroups consist of the nonnormal subgroups, plus $G$ and the maximal normal subgroup $N$. If $H$ belongs to $\mathcal{I}$ then whenever $(K) \geq(H)$ necessarily $K \in \mathcal{I}$. This means that in the equations (3) corresponding to a subgroup $H$ in $\mathcal{I}$ the only non-zero coefficients of the $y_{K}$ 's are those $K \in \mathcal{I}$. That is, the integers $y_{K}$ with $K \in \mathcal{I}$ are completely determined once they solve the sub-system of equations

$$
\begin{equation*}
\forall(H) \leq(G), H \in \mathcal{I}: \quad \sum_{\substack{(K) \geq(H) \\ K \in \mathcal{I}}} y_{K}\left|\left(\frac{G}{K}\right)^{H}\right| \in\{0,2\} \tag{4}
\end{equation*}
$$

But because $\left|\left(\frac{G}{H}\right)^{H}\right|=\left|W_{G} H\right|$, on the diagonal of this sub-matrix there are only 1 's and one 2 (corresponding to $N$ ). Thus the matrix can be inverted, and the number of solutions in the $y_{K}$ is exactly $2^{k}+1$, i.e. the number of conjugacy classes in $\mathcal{I}$.

Now we show that every such $\left(2^{k}+1\right)$-tuple can be extended to a solution $y \in$ $\mathbb{Z}^{2^{k+1}}$, i.e. that given a solution of the restricted system (4) it is possible to define integers $y_{K}$ also for $K \notin \mathcal{I}$ such that the global equations (3) hold. If $K$ is a subgroup not in $\mathcal{I}$, then its order is odd. Moreover, for each $K$ there is a unique conjugacy class $\left(K^{\prime}\right)$ of subgroups of order $2|K|$. Define $y_{K}=-\frac{1}{2} y_{K^{\prime}}$. By assumption, if $H$ is in $\mathcal{I}$ then (3) is automatically satisfied. Otherwise, the equations can be written as follows:

$$
\begin{equation*}
\sum_{\substack{(K) \geq(H) \\ K \notin \mathcal{I}}} y_{K}\left[\left|\left(\frac{G}{K}\right)^{H}\right|+y_{K}^{\prime}\left|\left(\frac{G}{K^{\prime}}\right)^{H}\right|\right]+y_{N}\left|\frac{G}{N}\right|+y_{G} \in\{0,2\} . \tag{5}
\end{equation*}
$$

Now, because $H \triangleleft G$ we have for all $K$

$$
\left|\left(\frac{G}{K}\right)^{H}\right|=\left|\frac{G}{K}\right|=2\left|\frac{G}{K^{\prime}}\right|
$$

thus equation (5) can be written as

$$
\begin{equation*}
\sum_{\substack{(K) \geq(H) \\ K \notin \mathcal{I}}}\left[\left(-\frac{1}{2} y_{K}^{\prime}\right) 2\left|\frac{G}{K^{\prime}}\right|+y_{K}^{\prime}\left|\frac{G}{K^{\prime}}\right|\right]+y_{N}\left|\frac{G}{N}\right|+y_{G} \in\{0,2\} \tag{6}
\end{equation*}
$$

that is $2 y_{N}+Y_{G} \in\{0,2\}$, and this is certainly true because it is equation (4) with $H=N$.

As a consequence, the number of generators of the Burnside ring is exactly $2^{k}+1$, i.e. the claim.

## 6. The derived length

The collection of the previous propositions can easily be seen as a proof of the first part of Theorem 1. There is only to give the lower bound of the derived length $l(\operatorname{ker} I)$. So consider once more the abelian series ker $r_{i}$ in ker $I$ defined in the proof of Proposition 3. Let $d$ denote the maximum dimension of a sphere fixed by a subgroup $K$ with $\gamma_{K} \geq 2$. In our case, $d=k-1$. If $k=2$, then $\operatorname{ker} I=\mathbb{Z}^{3}$ and $l(\operatorname{ker} I)=1$, being abelian. So from now on, assume $k \geq 3$.

## Proposition 8

For every $i=1 \ldots d-1$ the group $\operatorname{ker} r_{i-1} / \operatorname{ker} r_{i+1}$ is non-abelian.

Proof. The group ker $r_{i-1} / \operatorname{ker} r_{i+1}$ by definition is isomorphic to the image of $\operatorname{ker} r_{i-1}$ under the restriction homomorphism $r_{i+1}$; that is, its elements can be seen as homotopy classes of isotropy stratification preserving equivariant (with respect to the Weyl group action) self-equivalences defined on fixed spheres of dimension $i+1$, that are the identity whenever restricted to spheres of dimension $i-1$ and such that the restriction to any single sphere of dimension $i+1$ or $i$ has degree 1 . The group $\operatorname{ker} r_{i-1} / \operatorname{ker} r_{i}$ can be embedded in $\operatorname{ker} r_{i-1} / \operatorname{ker} r_{i+1}$ as follows: an element is, as above, a class of orientation-preserving self-equivalences on $X^{i}$ that fix $X^{i-1}$ and that have degree 1 whenever restricted to single spheres of dimension $i$. Let $f_{0}$ denote such a map. We will extend $f_{0}$ to a map $f$ on $X^{i+1}$.

Let $X^{K}$ be a sphere of dimension $i+1$ in $X^{d}$; the singular set $X_{s}^{K}$ is equal to the intersection of $X^{K}$ with $X^{i}$, therefore $f_{s}^{K}$ is defined as the restriction of $f_{0}$. If $\gamma_{K}=1$, then there is a single map with the appropriate degree, and therefore $f$ can be defined on $X^{K}$. Otherwise, $X_{s}^{K}$ is the union of $i+2$ spheres of dimension $i$ in $X^{K}$, which divide $X^{K}$ into $\gamma_{K}=2^{i+2}$ components.

Every component of $X_{K}$ is homeomorphic to the interior of a $i+1$-simplex $\Delta_{i+1}$, and the interiors of its $i+2 i$-dimensional faces are components of $X^{K} \cap X^{i} \backslash X^{i-1}$. The total amount of such faces for all the components of $X_{K}$ is therefore $(i+2) 2^{i+1}$.

So let $\Delta_{i+1}$ be one of the components of $X_{K}$ and $\Delta_{i+1} \times I$ the cartesian product with the unit interval. We first define a map $f_{c}$ on $\Delta_{i+1} \times\{0\} \cup \partial \Delta_{i+1} \times I$, and then by composition with the cylinder map

$$
\Delta_{i+1} \rightarrow \Delta_{i+1} \times\{0\} \cup \partial \Delta_{i+1} \times I
$$

we obtain a map on $\Delta_{i+1}$. The map $f_{c}$ is defined by $f_{c}(x, t)=x$ if $x \in \Delta_{i+1} \cap X^{i-1}$ or $t=0$; else, $f_{c}(x, 1)=f_{s}^{K}$ if $x \in \partial \Delta_{i+1}=\Delta_{i+1} \cap X_{s}^{K}$. The side-faces of the cylinder are of the form $\Delta_{i} \times I$, where $\Delta_{i}$ is a $i$-simplex in $\Delta_{i+1}$. The map on the boundary of $\Delta_{i} \times I$ is thus defined, and attains its values outside inside the sphere $S^{i}$ in $X^{K}$ containing $\Delta_{i}$. It is therefore possible to extend $f_{c}$ in a unique (up to homotopy) way such that the image of $\Delta_{i} \times I$ does not contain any point of the component of the complement of $S^{i}$ containing $\Delta_{i+1}$. Doing this for all the faces of $\Delta_{i+1}$, and for all the
possible components $\Delta_{i+1}$ in $X_{K}$ gives a well-defined map $f^{K}$. The degree in $\Delta_{i+1}$ of $f^{K}$ relative to a regular point $x \in X_{K}$ is, by construction, equal to

$$
\operatorname{deg}\left(f^{K} \mid \Delta_{i+1} ; x\right)= \begin{cases}1 & \text { if } x \in \Delta_{i+1}  \tag{7}\\ -\sum_{\Delta_{i} \in \partial \Delta_{i+1}} w_{f}\left(\Delta_{i}\right) \cdot \chi_{\Delta_{i+1}, \Delta_{i}}(x) & \text { if } x \in X_{K} \backslash \Delta_{i+1}\end{cases}
$$

where $\chi_{\Delta_{i+1}, \Delta_{i}}(x)$ is defined to be, 0 or 1 if $x$ respectively is or is not in the same component of $X^{K} \backslash S^{i}$ as $\Delta_{i+1}$, and $S^{i}$ as above is the $i$-sphere containing $\Delta_{i} ; f_{\Delta_{i}}$ denotes the map $f_{0}$ restricted to the sphere $S^{i}$; furthermore, $w_{f}\left(\Delta_{i}\right)$ denotes the degree $\operatorname{deg}\left(f_{\Delta_{i}} \mid \Delta_{i} ; x^{\prime} \in S^{i} \backslash \Delta_{i}\right)$. Then by construction

$$
\sum_{\Delta_{i} \in S^{i}}-w_{f}\left(\Delta_{i}\right)=\operatorname{deg}\left(f_{\Delta_{i}}\right)-1=0
$$

and summing the equations in (7) allows to conclude that $\operatorname{deg}\left(f^{K}\right)=1$.
We have proved that this construction gives an embedding, not a homomorphism. In fact, as seen in Remark 1, it is not a homomorphism.

Now let $S^{i}$ one of the $i$-spheres in $X^{K}$ for a $K$, and let $\bar{\Delta}_{i}$ and $\bar{\Delta}_{i}^{\prime}$ two consecutive $i$-faces in $S^{i}$. Let $\varphi: S^{i} \rightarrow S^{i}$ be the map which is the identity whenever restricted to $S^{i} \cap X^{i-1}$, such that the degree of $\varphi$ in $\bar{\Delta}_{i}$ relative to a point in $\bar{\Delta}_{i}^{\prime}$ is 1 , and the degree in $\bar{\Delta}_{i}^{\prime}$ relative to a point in $\bar{\Delta}_{i}$ is -1 . It is a stratified self-equivalence of $S^{i}$, with as inverse the map constructed in the same way but exchanging the roles of $\bar{\Delta}_{i}$ and $\bar{\Delta}_{i}^{\prime}$. Extend it then to $f_{s}^{K}$, being it the identity on the other spheres in $X_{s}^{K}$, and to a $\operatorname{map} f^{K}: X^{K} \rightarrow X^{K}$ with the procedure above described. Let $\varphi^{\prime}$ the map $X^{K} \rightarrow X^{K}$ obtained in the same fashion, by starting with the inverse of the equivalence $\varphi$ in $S^{i}$, instead. To show that actually $\varphi^{\prime}$ is the inverse of $\varphi$ (as stratified maps of $\left.X^{K}\right)$, it is sufficient to show that the composition $\varphi \varphi^{\prime}$ is homotopic (relative to the stratification) to the identity. We again use the local degrees:

$$
\begin{aligned}
& \operatorname{deg}\left(\varphi \varphi^{\prime} \mid \Delta_{i+1}^{\prime} ; \Delta_{i+1}^{\prime \prime}\right) \\
&= \sum_{\Delta_{i+1}} \operatorname{deg}\left(\varphi \mid \Delta_{i+1} ; \Delta_{i+1}^{\prime \prime}\right) \cdot \operatorname{deg}\left(\varphi^{\prime} \mid \Delta_{i+1}^{\prime} ; \Delta_{i+1}\right) \\
&= \sum_{\substack{\Delta_{i+1} \neq \Delta_{i+1}^{\prime} \\
\Delta_{i+1} \neq \Delta_{i+1}^{\prime \prime}}} \sum_{\substack{\Delta_{i} \in \Delta \Delta_{i+1} \\
\Delta_{i}^{\prime} \in \Delta_{i+1}^{\prime}}} w_{\varphi}\left(\Delta_{i}\right) w_{\varphi^{\prime}}\left(\Delta_{i}^{\prime}\right) \chi_{\Delta_{i+1}, \Delta_{i}}\left(\Delta_{i+1}^{\prime \prime}\right) \chi_{\Delta_{i+1}^{\prime}, \Delta_{i}^{\prime}}\left(\Delta_{i+1}\right) \\
& \quad+\operatorname{deg}\left(\varphi \mid \Delta_{i+1}^{\prime \prime} ; \Delta_{i+1}^{\prime \prime}\right) \operatorname{deg}\left(\varphi^{\prime} \mid \Delta_{i+1}^{\prime} ; \Delta_{i+1}^{\prime \prime}\right) \\
&\left(+\operatorname{deg}\left(\varphi \mid \Delta_{i+1}^{\prime} ; \Delta_{i+1}^{\prime \prime}\right) \operatorname{deg}\left(\varphi^{\prime} \mid \Delta_{i+1}^{\prime} ; \Delta_{i+1}^{\prime}\right)\right)
\end{aligned}
$$

The last term, of course, occurs if and only if $\Delta_{i+1}^{\prime} \neq \Delta_{i+1}^{\prime \prime}$. In this case, the sum of the two last terms vanishes; but the first sum can be written as

$$
\begin{aligned}
& \sum_{\Delta_{i}^{\prime} \in \partial \Delta_{i+1}^{\prime}} w_{\varphi^{\prime}}\left(\Delta_{i}^{\prime}\right)\left(\sum_{\substack{\Delta_{i+1} \neq \Delta_{i+1}^{\prime} \\
\Delta_{i+1} \neq \Delta_{i+1}^{\prime \prime}}} \sum_{\Delta_{i} \in \partial \Delta_{i+1}} w_{\varphi}\left(\Delta_{i}\right)\right. \\
&\left.\times \chi_{\Delta_{i+1}, \Delta_{i}}\left(\Delta_{i+1}^{\prime \prime}\right) \chi_{\Delta_{i+1}^{\prime}, \Delta_{i}^{\prime}}\left(\Delta_{i+1}\right)\right)
\end{aligned}
$$

moreover, the product $w_{\varphi}\left(\Delta_{i}\right) w_{\varphi^{\prime}}\left(\Delta_{i}^{\prime}\right)$ is different than zero if and only if both $\Delta_{i}$ and $\Delta_{i}^{\prime}$ belong to the set $\left\{\bar{\Delta}_{i}, \bar{\Delta}_{i}^{\prime}\right\}$; thus, for such terms in the sum the product

$$
\chi_{\Delta_{i+1}, \Delta_{i}}\left(\Delta_{i+1}^{\prime \prime}\right) \chi_{\Delta_{i+1}^{\prime}, \Delta_{i}^{\prime}}\left(\Delta_{i+1}\right)
$$

is equal to one if and only if $\Delta_{i+1}^{\prime}$ and $\Delta_{i+1}^{\prime \prime}$ both belong to the same component of $X^{K} \backslash S^{i}$ (where $S^{i}$ is the sphere containing $\Delta_{i}$. This immediately implies that if $\Delta_{i+1}^{\prime}$ and $\Delta_{i+1}^{\prime \prime}$ do not belong to the same component, then $\operatorname{deg}\left(\varphi \varphi^{\prime} \mid \Delta_{i+1}^{\prime} ; \Delta_{i+1}^{\prime \prime}\right)=0$. Otherwise, there are just two non-zero terms in the sum, i.e. those corresponding to the two components $\Delta_{i+1}$ such that $\bar{\Delta}_{i} \in \partial \Delta_{i+1}$ or $\bar{\Delta}_{i}^{\prime} \in \partial \Delta_{i+1}$. But by definition the sum $w_{\varphi}\left(\Delta_{i}\right)+w_{\varphi}\left(\Delta_{i}^{\prime}\right)$ vanishes, and hence $\operatorname{deg}\left(\varphi \varphi^{\prime} \mid \Delta_{i+1}^{\prime} ; \Delta_{i+1}^{\prime \prime}\right)=0$. With a similar argument it is easy to show that $\operatorname{deg}\left(\varphi \varphi^{\prime} \mid \Delta_{i+1}^{\prime} ; \Delta_{i+1}^{\prime}\right)=1$, that is, $\varphi^{\prime}$ is the (stratified homotopical) inverse of $\varphi$.

Now, consider a self-equivalence of degree one $m: X^{K} \rightarrow X^{K}$ which extends the identity on $X_{s}^{K}$; let $M\left(\Delta_{i+1}, \Delta_{i+1}^{\prime}\right)$ denote the degree of $m$ restricted to a component $\Delta_{i+1}$ relative to a point in $\Delta_{i+1}^{\prime}$. As a matrix, $M$ is of the form $I+M_{0}$, where $M_{0}$ is a matrix such that $M_{0}\left(\Delta_{i+1}, \Delta_{i+1}^{\prime}\right)$ does not depend upon $\Delta_{i+1}^{\prime}$ and with trace equal to 0 . Every matrix $M_{0}^{\prime}$ with integer coefficients, constant columns and trace 0 can occur as a degrees matrix $I+M_{0}^{\prime}$ for some self-equivalence.

We want to show that $\varphi m \nsim m \varphi$. To do that, it is better to simplify the procedures used above (see also Remark 1 below). Let $K$ denote the matrix of degrees of $\varphi$ and $M$ the matrix of degrees of $m$. Then $M=I+M_{0}$ for a matrix $M_{0}$ with constant columns and trace 0 , and $K=I+K_{0}$, where $K_{0}$ is a matrix with just 4 columns different than zero (the ones corresponding to the components $\Delta_{i+1}$ such that $\partial \Delta_{i+1} \cap\left\{\bar{\Delta}_{i}, \bar{\Delta}_{i}^{\prime}\right\}$ is not empty); the values in the column relative to a component $\Delta_{i+1}$ containing e.g. $\bar{\Delta}_{i}$ are all 0 for those rows corresponding to a $\Delta_{i+1}^{\prime \prime}$ on the same component in $X^{K} \backslash S^{i}$ of $\Delta_{i+1}$, otherwise equal to $-w_{\varphi}\left(\bar{\Delta}_{i}\right)$. Looking at rows, it is easy to see that in any row of $K_{0}$ there are exactly 2 non-zero values, one +1 and one -1 (see for example the matrices occurring in Remark 1).

Now, because of the property of rows of $K_{0}$ and columns of $M_{0}, K_{0} M_{0}=0$. On the other hand $M_{0} K_{0}$ is the zero matrix if and only if the trace of the matrix $M_{0}^{\prime}$, obtained by deleting all the rows and columns corresponding to components $\Delta_{i+1}$ belonging to one of the two components of $X^{K} \backslash S^{i}$, is zero. But it's clear that it is possible to select $M_{0}$ in a way that this does not occur: for example, $M_{0}$ might have just two columns, one full of 1's, corresponding to a $\Delta_{i+1}$, and one full of -1 's, corresponding to a $\Delta_{i+1}^{\prime}$ on the different component in $X^{K} \backslash S^{i}$. Thus $f m \sim m f$ if and only if

$$
\left(I+K_{0}\right)\left(I+M_{0}\right)-\left(I+M_{0}\right)\left(I+K_{0}\right)=K_{0} M_{0}-M_{0} K_{0}=0
$$

but $K_{0} M_{0}-M_{0} K_{0}=M_{0} K_{0} \neq 0$, and hence $f m \nsim m f$.
To complete the proof, it suffices to extend such maps to the whole $X^{i+1}$ as the identity outside $X^{K}$ : for the same reason, it occurs that for all $i$ the group $\operatorname{ker} r_{i-1} / \operatorname{ker} r_{i+1}$ is not commutative.

We are now in the position to finish the proof of Theorem 1. Applying Proposition 8 , it is seen that the abelian series

$$
1=\operatorname{ker} r_{d} \triangleleft \operatorname{ker} r_{d-1} \triangleleft \ldots \triangleleft r_{0}=\operatorname{ker} I
$$

has non-abelian consecutive factors ker $r_{i-1} / \operatorname{ker} r_{i+1}$. Therefore its derived length must be at least $(d+1) / 2$. Being $d=k-1$, the derived length $l(\operatorname{ker} I)$ is thus at least $k / 2$. The proof of the theorem is finished.

## 7. Remarks

Remark 1. The extension procedure used in the proof of Proposition 8 actually does not yield an homomorphism. To see the reason, consider two maps $\varphi_{1}$ and $\varphi_{2}$ defined in the same way as $\varphi$ above, with the faces $\bar{\Delta}_{i}$ and $\bar{\Delta}_{i}^{\prime}$ used for $\varphi_{1}$ different than the ones used for the definition of $\varphi_{2}$. For example, in a 2 -sphere $X^{K}$, let $1 \ldots 8$ denote the components of $X^{K} \cap X^{1}$, such that $\{1,2,3,4\}$ is the upper hemisphere, $\{1,2,5,6\}$ the East hemisphere and $\{2,3,6,7\}$ the North hemisphere (assume the East-Nord plane to be horizontal). Then $\varphi_{1}$, defined using the faces $\{1,4\}$ and $\{5,8\}$ (i.e. the faces belonging to the boundaries of 1 and 4 , or 5 and 8 ), has matrix form $I+K_{1}$, with

$$
K_{1}=\left(\begin{array}{cccccccc}
0 & 0 & 0 & 0 & 1 & 0 & 0 & -1 \\
0 & 0 & 0 & 0 & 1 & 0 & 0 & -1 \\
0 & 0 & 0 & 0 & 1 & 0 & 0 & -1 \\
0 & 0 & 0 & 0 & 1 & 0 & 0 & -1 \\
1 & 0 & 0 & -1 & 0 & 0 & 0 & 0 \\
1 & 0 & 0 & -1 & 0 & 0 & 0 & 0 \\
1 & 0 & 0 & -1 & 0 & 0 & 0 & 0 \\
1 & 0 & 0 & -1 & 0 & 0 & 0 & 0
\end{array}\right)
$$

Using the faces $\{2,3\}$ and $\{6,7\}$ instead, the matrix form is $I+K_{2}$, with

$$
K_{2}=\left(\begin{array}{cccccccc}
0 & 0 & 1 & 0 & 0 & 0 & -1 & 0 \\
0 & 0 & 1 & 0 & 0 & 0 & -1 & 0 \\
0 & 1 & 0 & 0 & 0 & -1 & 0 & 0 \\
0 & 1 & 0 & 0 & 0 & -1 & 0 & 0 \\
0 & 0 & 1 & 0 & 0 & 0 & -1 & 0 \\
0 & 0 & 1 & 0 & 0 & 0 & -1 & 0 \\
0 & 1 & 0 & 0 & 0 & -1 & 0 & 0 \\
0 & 1 & 0 & 0 & 0 & -1 & 0 & 0
\end{array}\right)
$$

Since $K_{1} K_{2}-K_{2} K_{1}$ is a matrix with 8 rows equal to the vector

$$
(1,-1,1,-1,-1,1,-1,1)
$$

$K_{1} K_{2}-K_{2} K_{1} \neq 0$, and so the composition $\left(I+K_{1}\right)\left(I+K_{2}\right)$ cannot be the map obtained using the procedure of above, starting from the restriction of the composition
$\varphi_{1} \varphi_{2}$, for the simple reason that the restrictions of $\varphi_{i}$ commute, while the maps $\varphi_{1}$ and $\varphi_{2}$ themselves not. In fact, these commute if and only if

$$
\left(I+K_{1}\right)\left(I+K_{2}\right)-\left(I-K_{1}\right)\left(I-K_{2}\right)=0 \Longleftrightarrow K_{1} K_{2}-K_{2} K_{1}=0
$$

Remark 2. The group of self-equivalences of $S^{1}$ fixing 4 distinct points (i.e. the first step in the inductive process of defining maps on $X_{k}$ ) is represented as follows: let $B$ denote the set of all the $4 \times 4$ matrices with integer coefficients that can be written as $I+M$, where $I$ is the identity matrix and $M$ any $4 \times 4$-matrix with constant columns and trace equal to -2 or 0 . Then, if $M_{1}$ and $M_{2}$ are such matrices, $M_{1} M_{2}=\operatorname{Tr}\left(\mathrm{M}_{1}\right) \mathrm{M}_{2}$, and

$$
\left(I+M_{1}\right)\left(I+M_{2}\right)=I+M_{1}+M_{2}+\operatorname{Tr}\left(\mathrm{M}_{1}\right) \mathrm{M}_{2}
$$

It is a group with respect to the product of matrices, isomorphic to $\mathbb{Z}^{3} \rtimes \mathbb{Z}_{2}$. The action of $\mathbb{Z}_{2}$ on $\mathbb{Z}^{3}$ is non-trivial, as can be seen by the fact that, if $\operatorname{Tr}(\mathrm{M})=0$ and $\operatorname{Tr}\left(\mathrm{M}_{2}\right)=-2$, then $I+M_{2}$ has order 2 and acts as

$$
\left(I+M_{2}\right)(I+M)\left(I+M_{2}\right)=I-M=(I+M)^{-1}
$$

But, taking local degrees, it is possible to see that $B$ is actually isomorphic to the group of self-equivalences fixing 4 points. Thus, by restricting to the sphere $S^{1} \subset X_{k}$ for some $k \geq 2$, the sequence $\mathbb{Z}^{3} \rightarrow B \rightarrow \mathbb{Z}_{2}$ is a homomorphic image of the sequence $\operatorname{ker} I \rightarrow \mathcal{E}_{G_{k}}\left(X_{k}\right) \rightarrow A(G)^{*}$. That is, $A(G)^{*}$ cannot be a direct factor of $\mathcal{E}_{G_{k}}\left(X_{k}\right)$ (but the torsion group of $\mathcal{E}_{G_{k}}\left(X_{k}\right)$ is still unknown).

Remark 3. The quotient $X_{2} / G_{2}$ is a sphere. To see that, proceed as follows: the group $G_{2}$ has polycyclic decomposition as $\mathbb{Z}_{3} \triangleleft \mathbb{Z}_{15} \triangleleft G_{2} . D(3,5) / \mathbb{Z}_{3}$ is a sphere (actually, it is a orbifold with a singular part of dimension 1 of cone points). Then $\mathbb{Z}_{15}$ acts on this quotient, again providing as a quotient a sphere with another circle of cone points. These two circles are linked in the resulting sphere, as well as their pre-images in $D(3,5)$. The last factor of the series is $\mathbb{Z}_{2}$ and the quotient of $D(3,5) /\left(\mathbb{Z}_{15}\right)$ under this action is again a sphere, with a third circle of cone points, which intersect the other two described above.

Another more general way of proving the same result is the following: consider the map

$$
\Lambda: D\left(j_{1}, \ldots, j_{k}\right) \rightarrow S^{2 k-1}
$$

defined by

$$
\Lambda:\left(z_{1}, \ldots, z_{k}\right) \mapsto\left(z_{1} \frac{z_{1}^{p_{1}-1}}{\left|z_{1}\right|^{p_{1}-1}}, \ldots, z_{k} \frac{z_{k}^{p_{k}-1}}{\left|z_{k}\right|^{p_{k}-1}}\right) \in S^{2 k-1} \subset \mathbb{C}^{k}
$$

It is easy to see that $\Lambda(x)=\Lambda(y)$ if and only if there is a power $\zeta_{n}^{\alpha}$ such that $y=\zeta_{n}^{\alpha} x$. Thus $\Lambda$ provides a homeomorphism from $D\left(j_{1}, \ldots, j_{k}\right) / N$ to $S^{2 k-1}$, where $N$ denotes the maximal cyclic normal subgroup of $G$. Furthermore, the $\Lambda$ is $G_{k}$-equivariant, if we define the action of $G$ on $S^{2 k-1}$ as $h\left(z_{1}, z_{2}, \ldots, z_{k}\right)=\left(\overline{z_{1}}, \ldots, \overline{z_{k}}\right)$ and $\zeta_{n} z=z$. The
quotient $X_{k} / G_{k}$ is thus equal to the quotient $S^{2 k-1} / h$, i.e. the join $\mathbb{R} P^{k-1} * S^{k-1}$; if $k=2$ then this is equal to the three-sphere $S^{1} * S^{1}=S^{3}$.
Remark 4. As we have seen in Section 2, there is a (unique) inclusion $G_{k} \hookrightarrow G_{k+1}$ and a (unique) projection $G_{k+1} \rightarrow G_{k}$, as long as an inclusion $X_{k} \hookrightarrow X_{k+1}$, which is $G_{k+1^{-}}$ equivariant (using the projection to let $G_{k+1}$ act on $X_{k}$ ). Thus $\mathcal{E}_{G_{k}}\left(X_{k}\right)=\mathcal{E}_{G_{k+1}}\left(X_{k}\right)$, and so there is a well-defined restriction $G_{k+1}$-homomorphism

$$
\mathcal{E}_{G_{k+1}}\left(X_{k+1}\right) \rightarrow \mathcal{E}_{G_{k}}\left(X_{k}\right)
$$

It is possible to see that it is onto, and that its kernel is an solvable non-abelian group with Hirsch length $23^{k}-2^{k}-1$.

The spheres $X_{k}$ can be seen as the a direct system $X_{k} \subset X_{k+1}$ of $G_{\infty^{\prime}}$-spheres, where $G_{\infty}$ is the direct limit of the $G_{k}$ 's. Let $X_{\infty}$ denote such limit. Using again the restriction homomorphism, there are surjective projections $\mathcal{E}_{G_{\infty}}\left(X_{\infty}\right) \rightarrow \mathcal{E}_{G_{k}}\left(X_{k}\right)$ for every $k$. Thus $\mathcal{E}_{G_{\infty}}\left(X_{\infty}\right)$ is a group with infinitely many generators.
Remark 5. It is also possible to consider the general case of the dihedral group $G=D_{2 n}$. The 3-dimensional dihedral sphere $D\left(q_{1}, q_{2}\right)$ defined as above might be of some interest by itself: if $q_{1}$ and $q_{2}$ are arbitrary integers such that $\left(q_{1}, n\right)=\left(q_{2}, n\right)=1$, then the quotient $D\left(q_{1}, q_{2}\right) / G$ is another (orbifold) sphere. The partial factorization

$$
D\left(q_{1}, q_{2}\right) \rightarrow D\left(q_{1}, q_{2}\right) / N \rightarrow D\left(q_{1}, q_{2}\right) / G
$$

where $N=<\zeta_{n}>\subset G$ is the normal $n$-cyclic subgroup, gives rise to two maps of degrees $n$ and 2 (the first is the covering)

$$
S^{3} \rightarrow L\left(n, q_{1}^{-1} q_{2}\right) \rightarrow S^{3}
$$

where $L\left(n, q_{1}^{-1} q_{2}\right)$ is the lens space and the inverse $q_{1}^{-1}$ is meant as inverse $\bmod n$. Another feature of this equivariant sphere is that the singular set of points of isotropy of order 2 is a link of $n$ circles, with linking numbers 1 . In case of $X_{2}$ these circles are not disjoint.

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